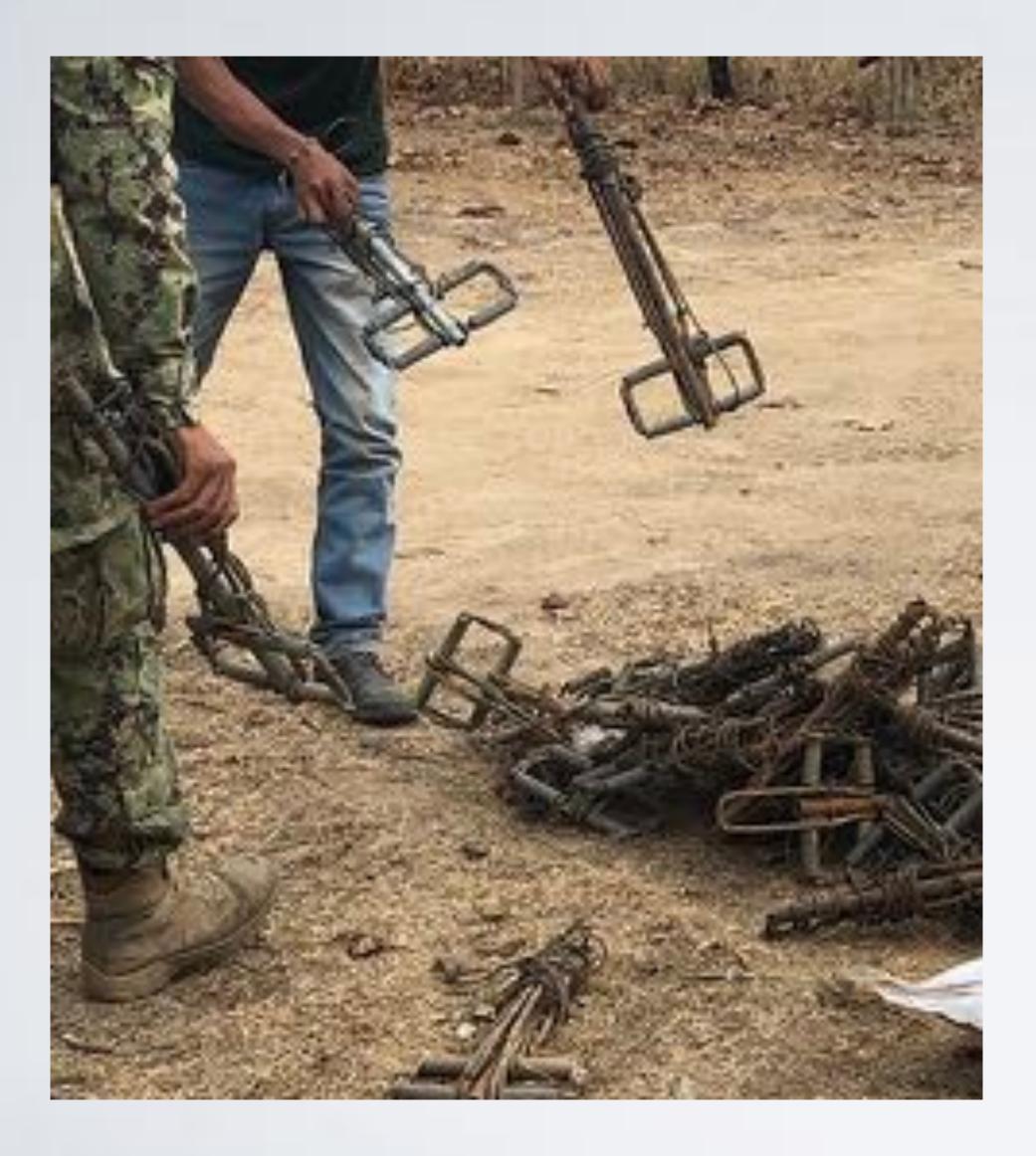
### Learning and Planning Under Uncertainty for Wildlife Conservation

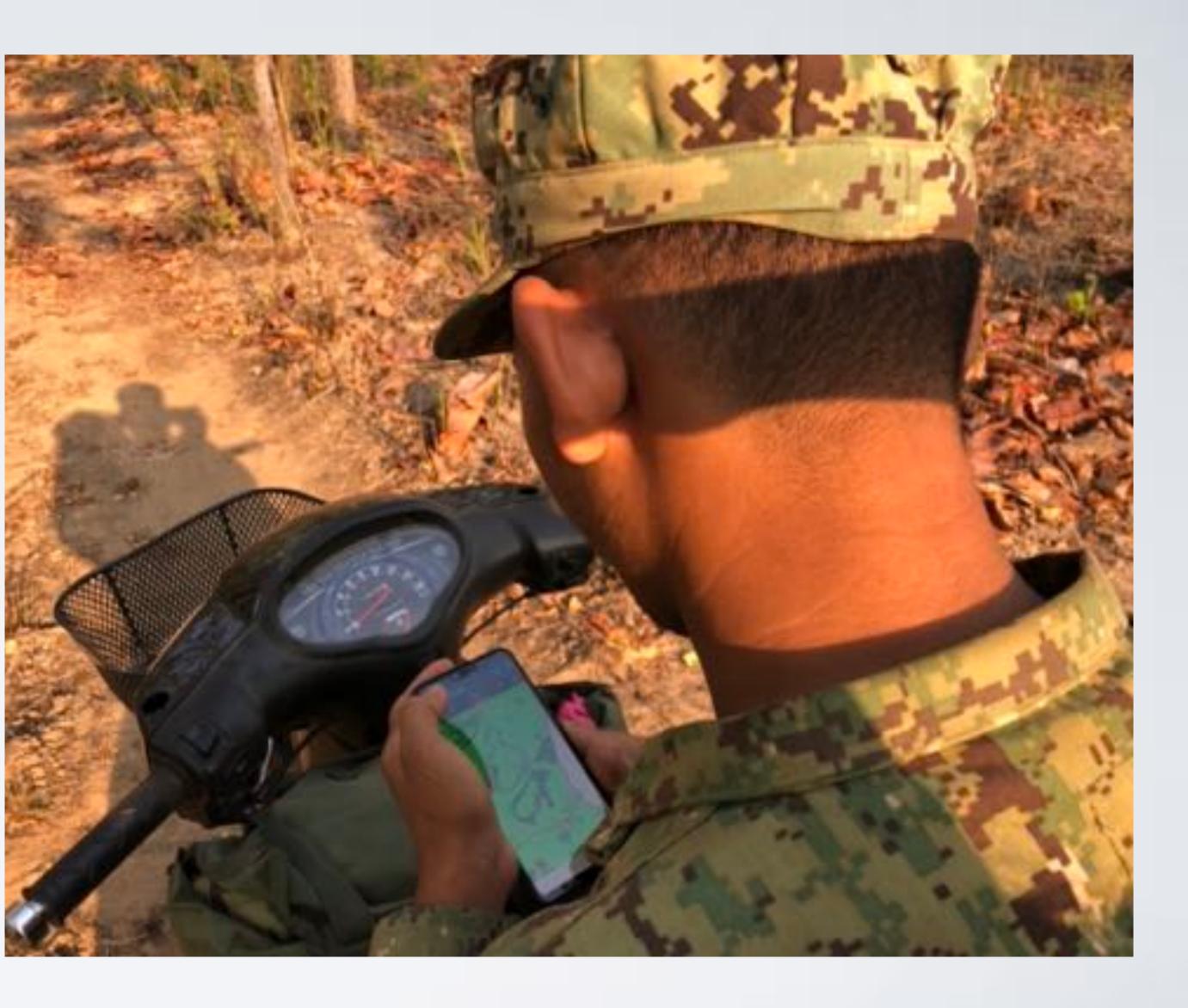


Al-Assisted Decision-Making for Conservation | October 20, 2022

**Lily Xu** Harvard University







#### Photos by Lily Xu

### Srepok Wildlife Sanctuary Cambodia

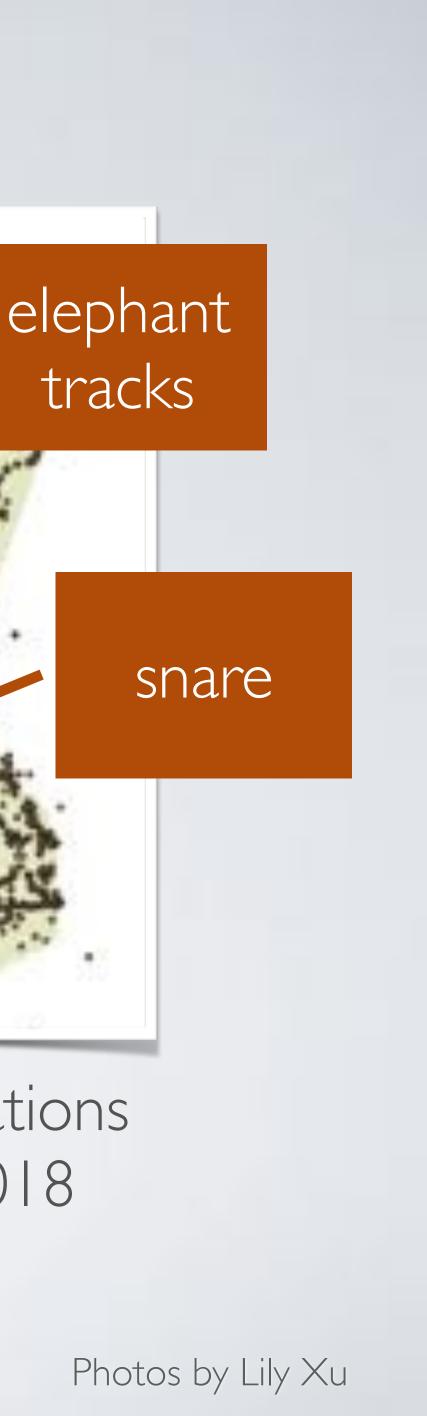




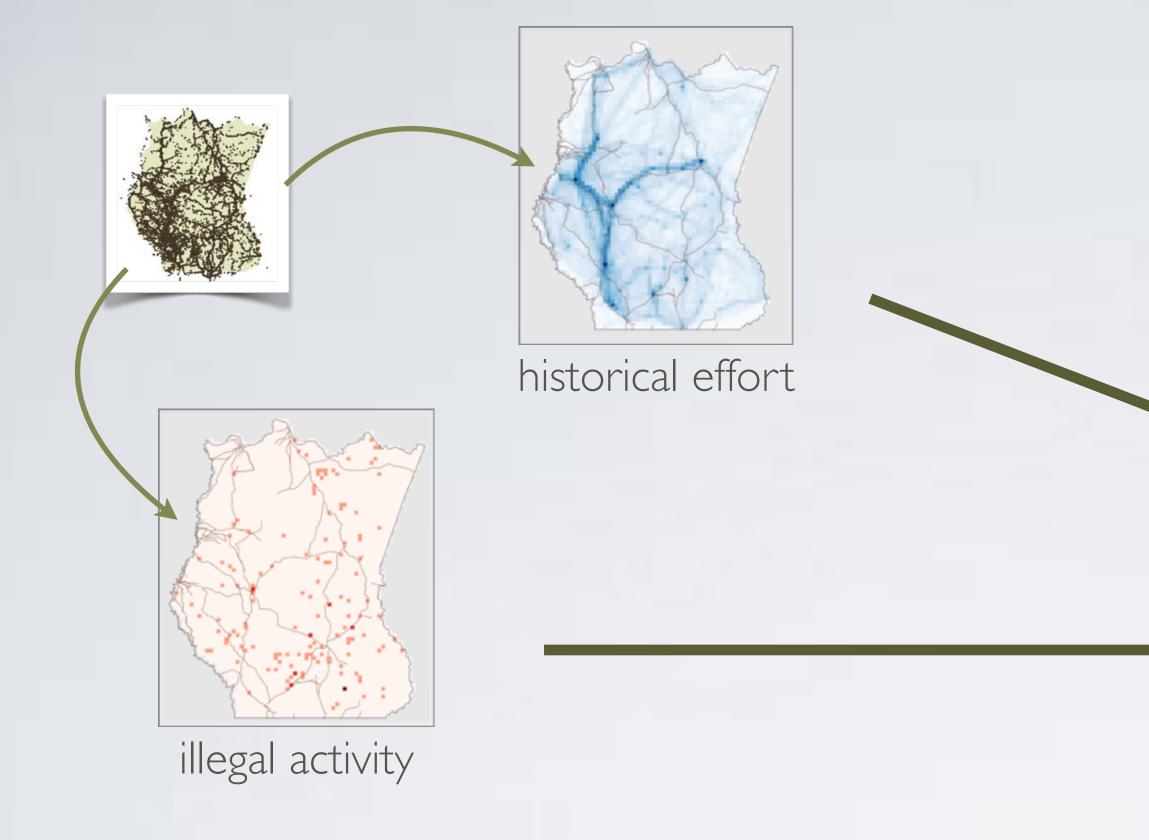


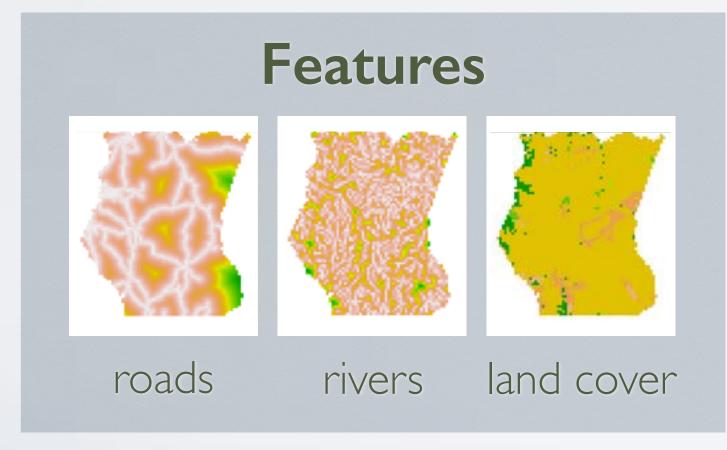


### illegal campsite



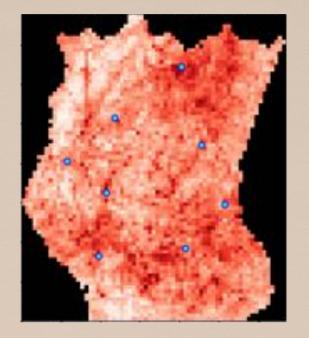
### 43,269 patrol observations recorded 2013 - 2018



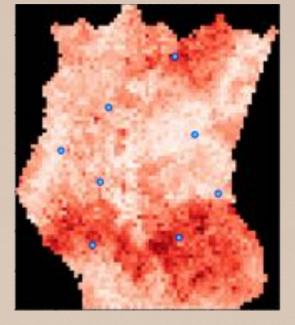


### **PAWS Overview** Protection Assistant for Wildlife Security

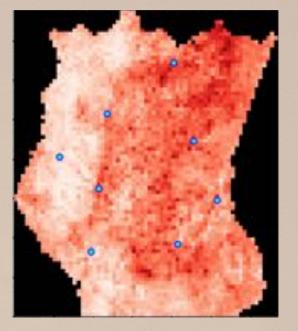
#### Predicted risk maps



overall risk

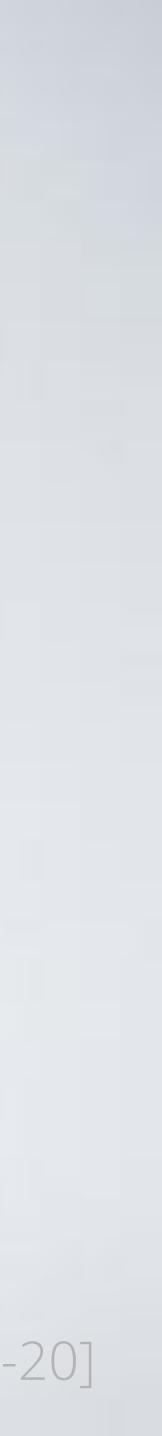


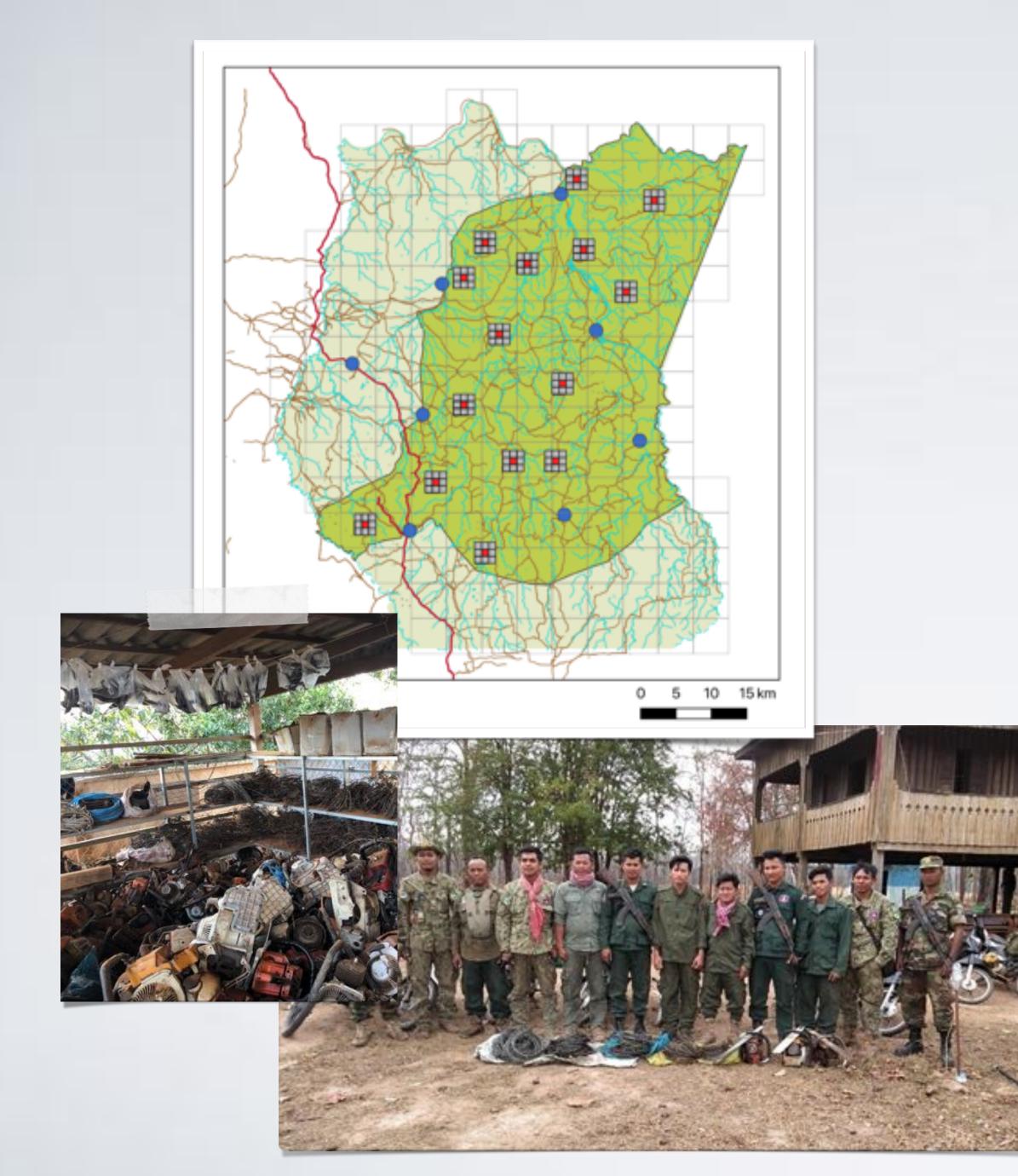
dry season



rainy season

#### [Xu et al., ICDE-20]





Photos by James Lourens and Lily Xu

#### Snares per sq. km patrolled

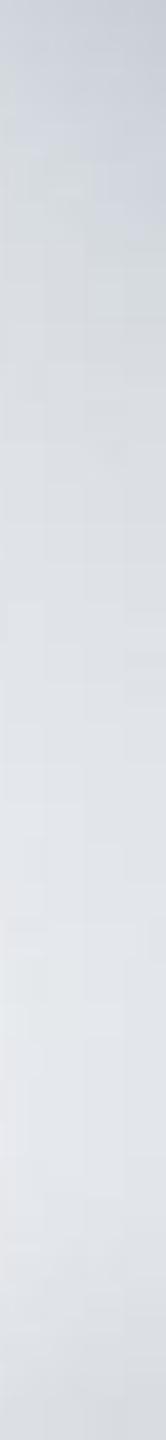


[Xu et al., ICDE-20]

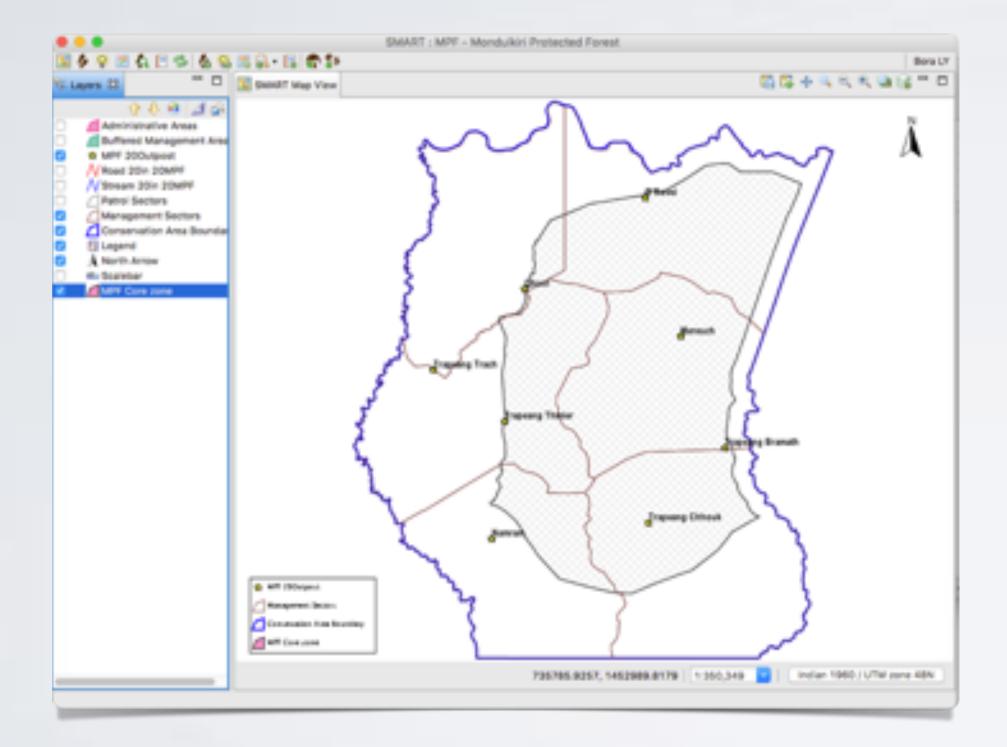




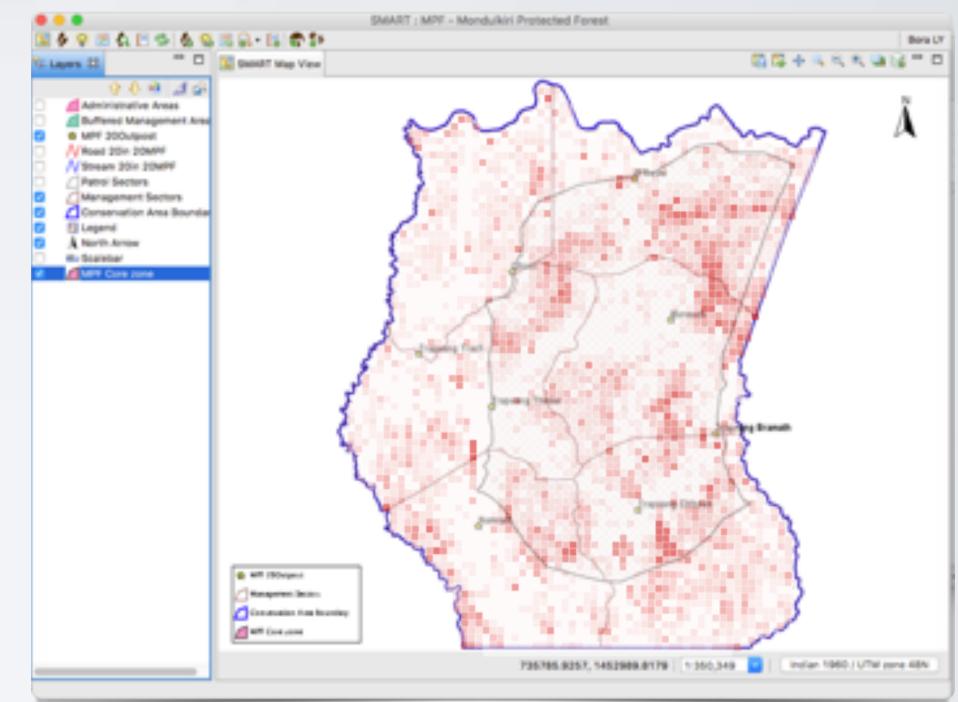
"I am super excited with the results. Let's get this going on other countries too this year." —Rohit Singh, WWF Zero Poaching Lead

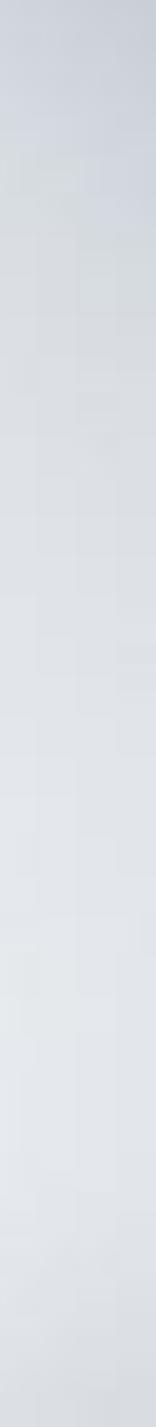




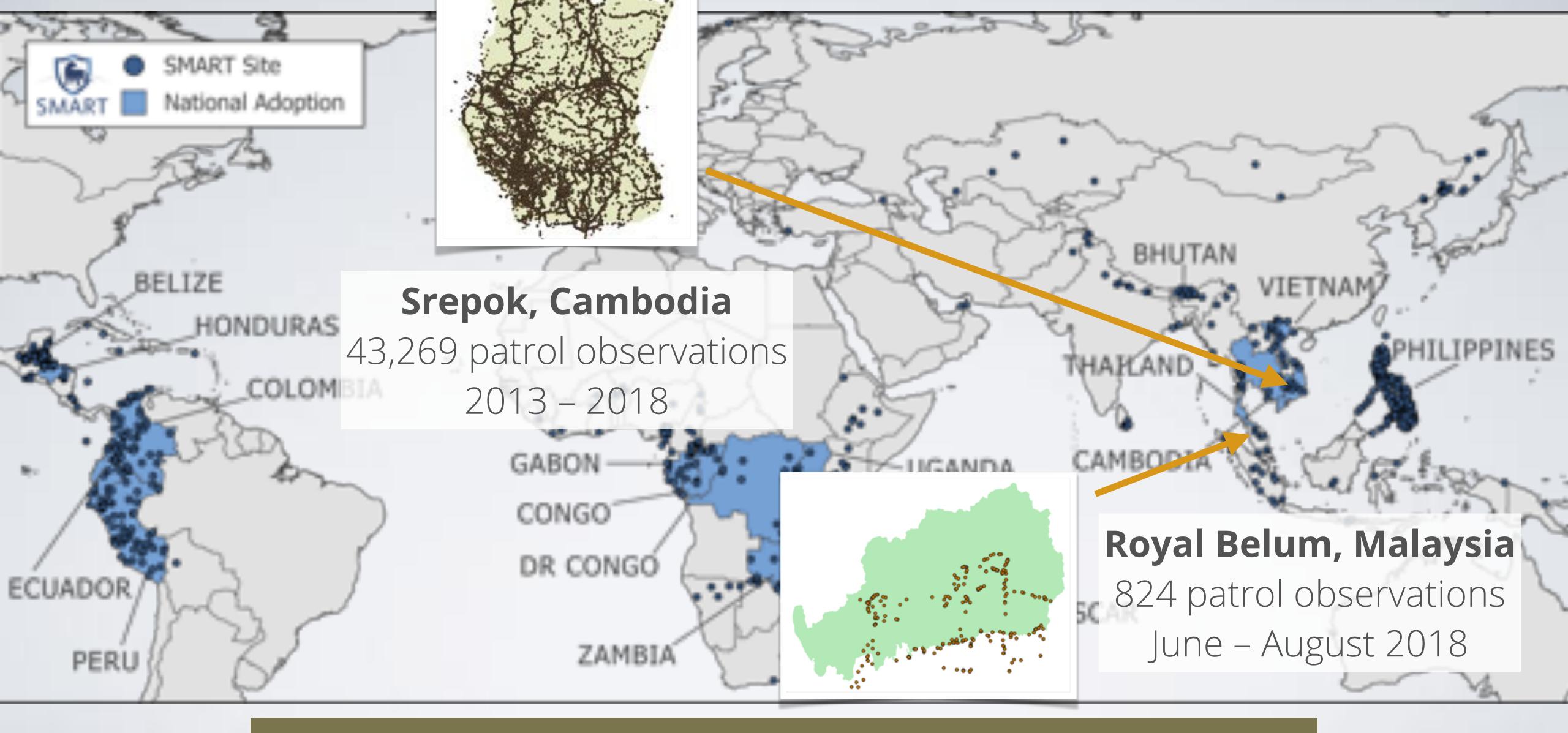






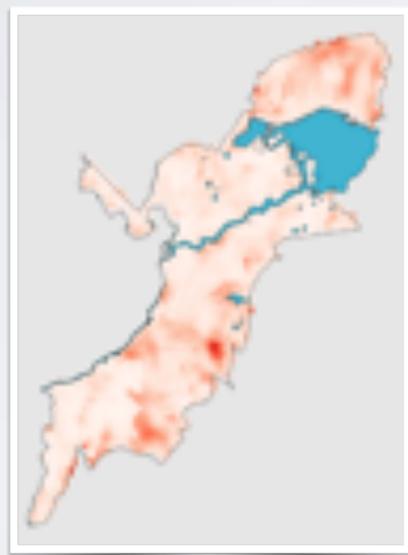


### Deployment to 1000+ protected areas



## Data-scarce parks: conduct patrols to detect illegal activity and improve the predictive model

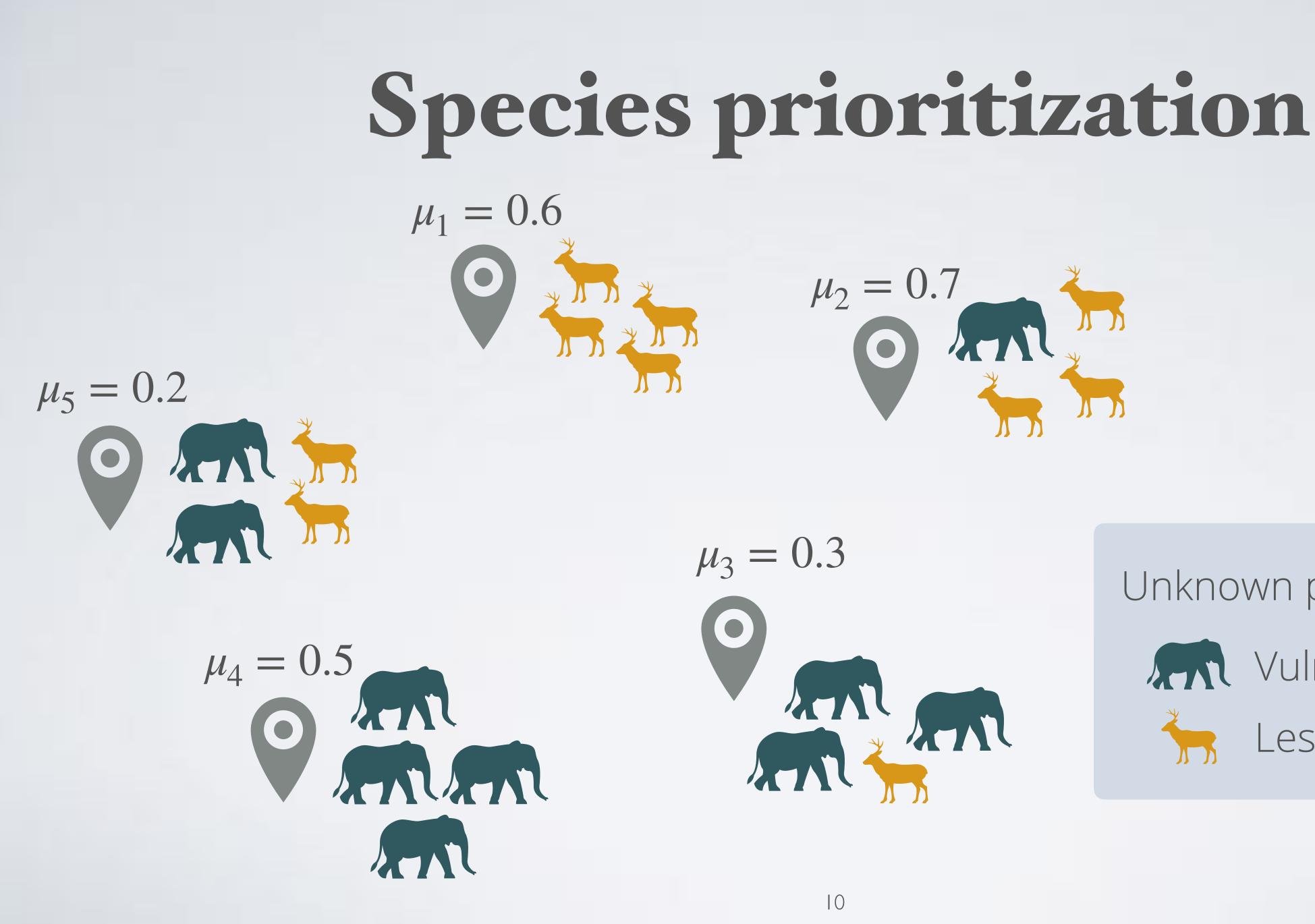
## The Dual Mandate exploitation Data-rich parks: build predictive models to plan patrols



#### exploration

[Xu et al., AAAI-21]



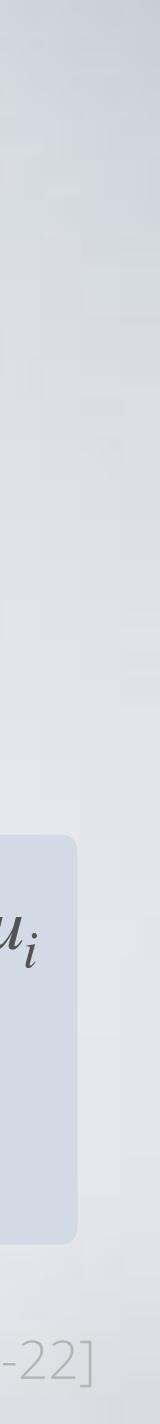


#### Unknown poaching prob $\mu_i$



Vulnerable Less vulnerable

[Xu et al., IJCAI-22]



### How do adversaries respond to our patrols?



#### [Xu et al., UAI-21]

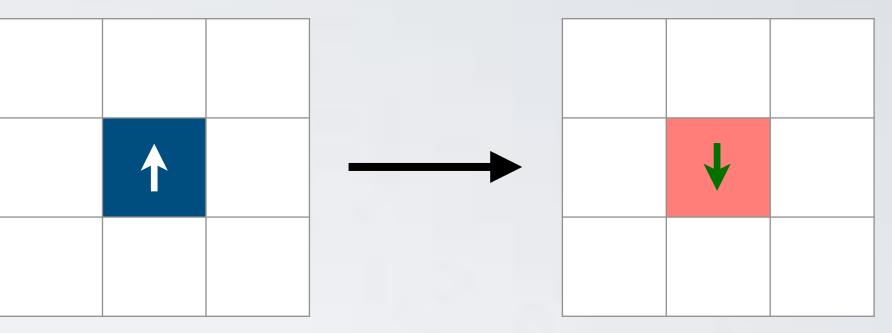


## Deterrence is key

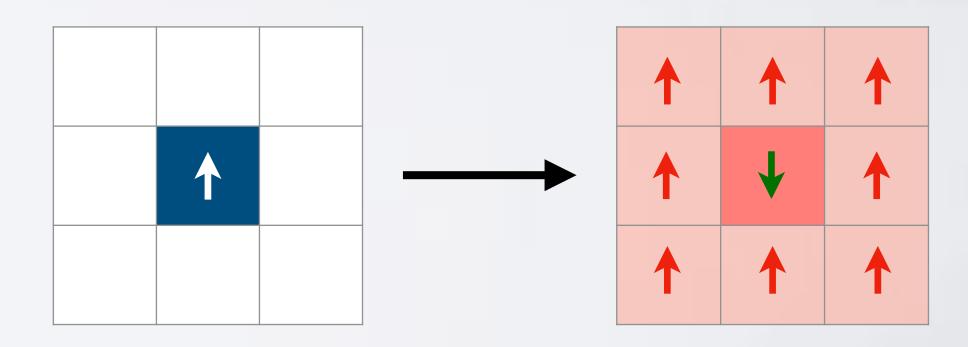


past patrol effort

illegal activity



deterrence

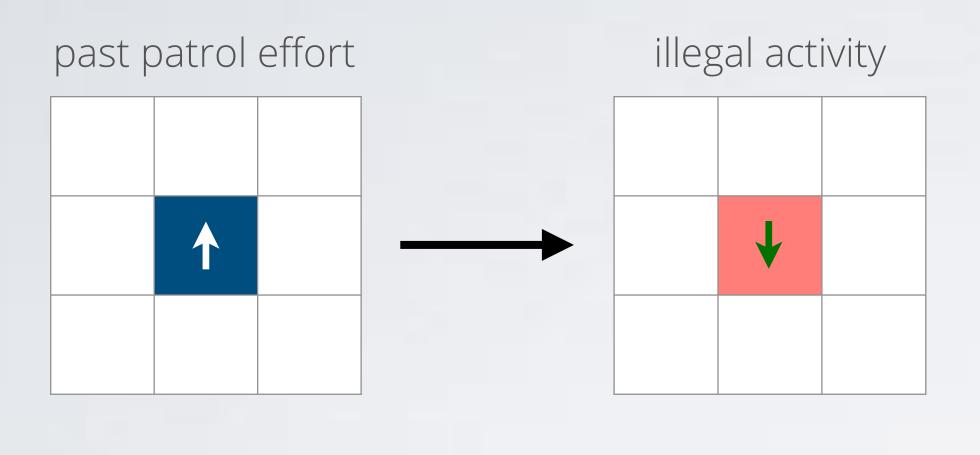


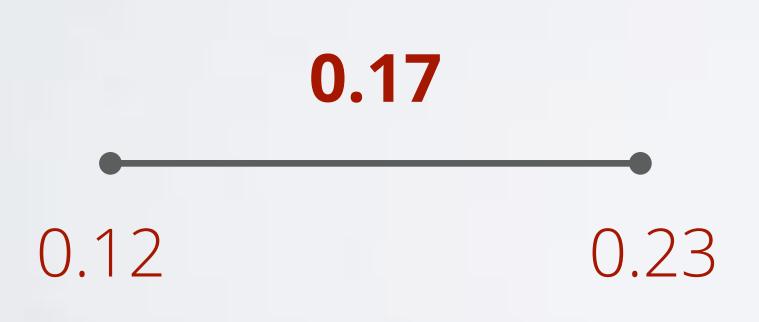
displacement





### Robust planning

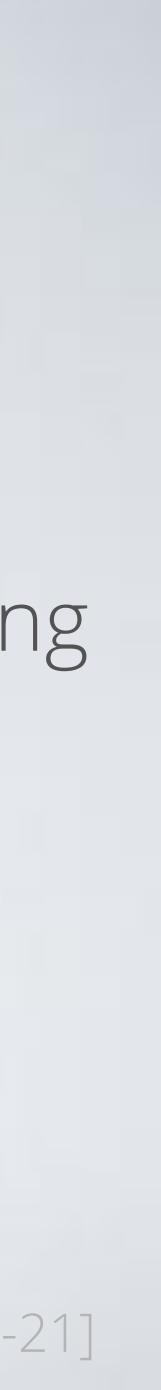


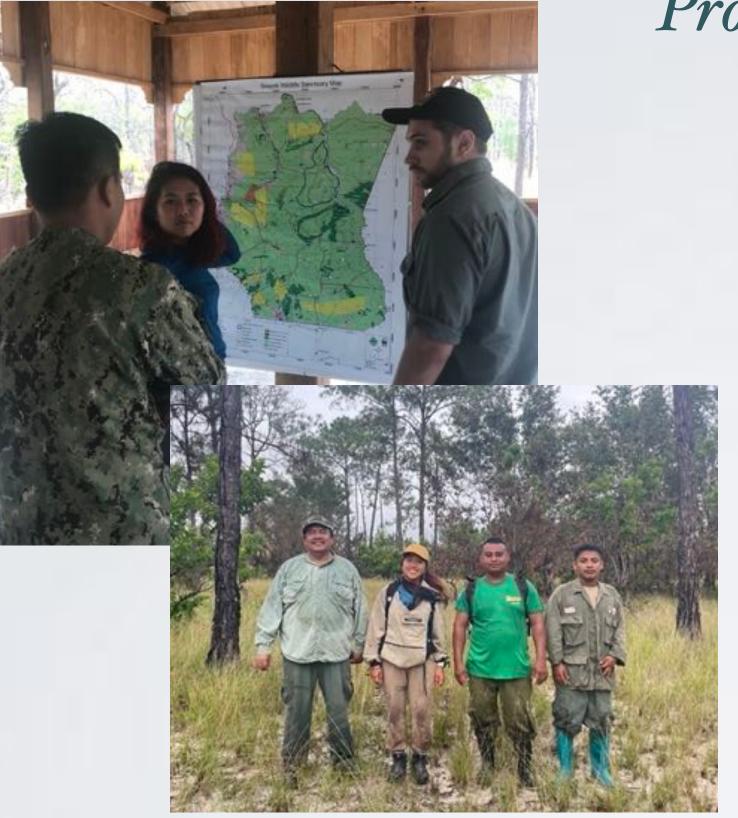


# **deterrence!** Sequential decision-making

# uncertainty? L robust patrol planning

[Xu et al., UAI-21]







### Collaboration with conservation NGOs









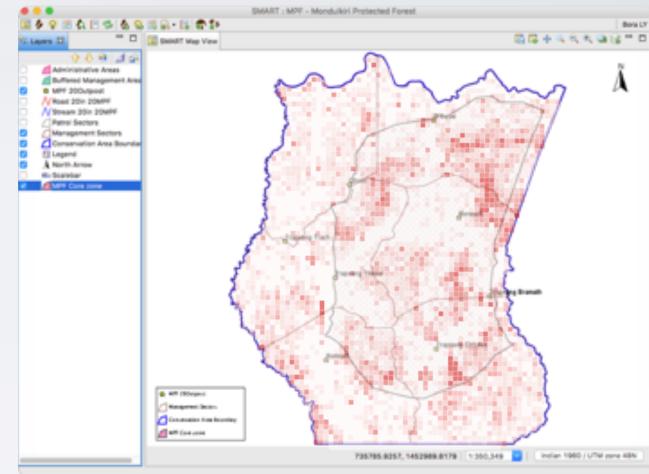


Field tests in Cambodia and Uganda [Xu et al., ICDE-20]

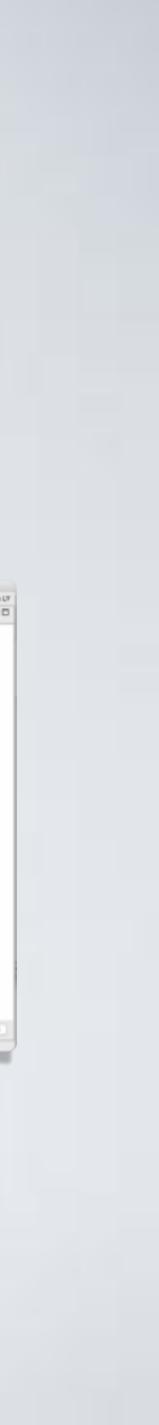


Protection Assistant for Wildlife Security

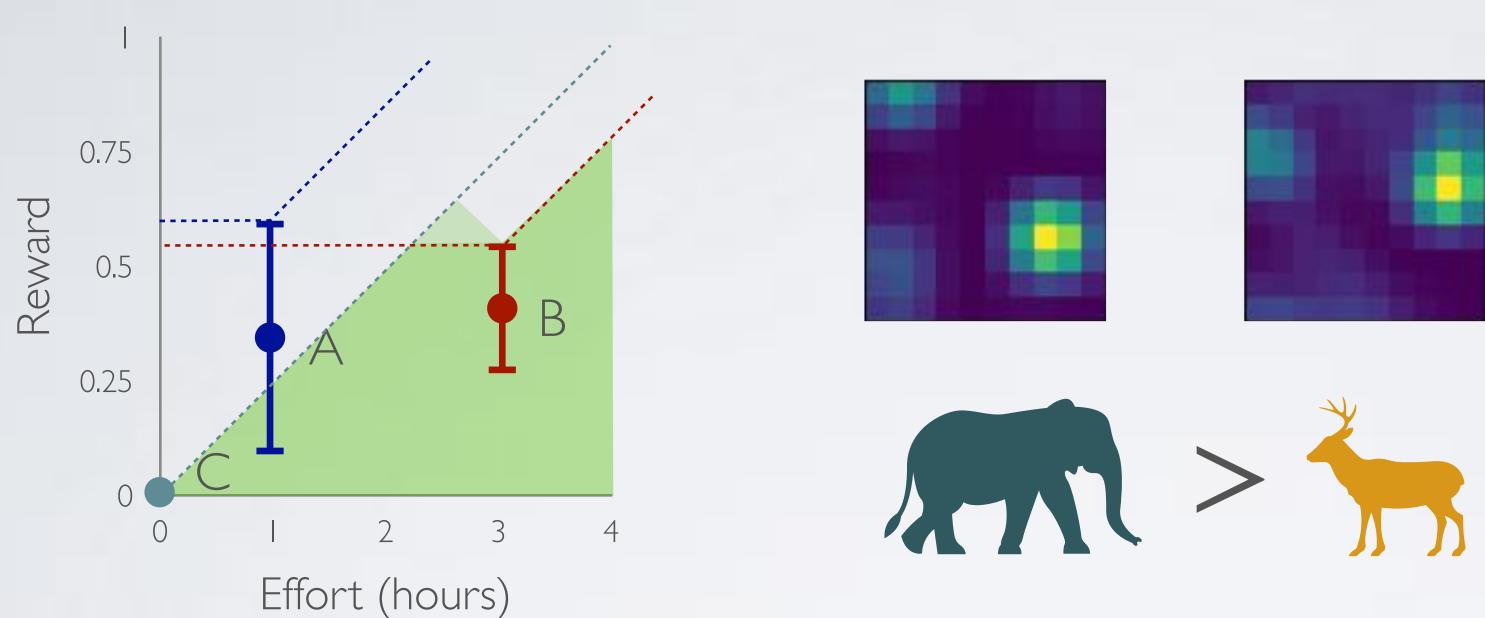




### Global deployment

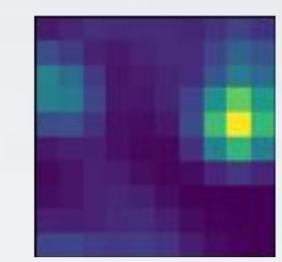


### New AI Methodology



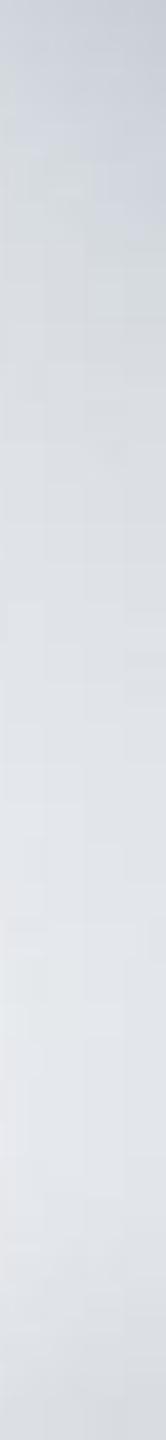
Multi-armed bandits to explore/exploit [Xu et al., AAAI-21]

Ranked prioritization with online allocation [Xu et al., IJCAI-22]



### **Agent oracle** ĨZ → $\rightarrow \pi$ DDPG Nature oracle $\widetilde{\pi}$ $\rightarrow$

Robust sequential decision-making [Xu et al., UAI-21]



### **AI for Conservation**



### Thanks to my collaborators and our conservation partners

Milind Tambe, Andrew Perrault, Fei Fang, Andy Plumptre, Andrew Davies, Luke Miratrix, Kai Wang, Elizabeth Bondi, Arpita Biswas, Diana Acosta-Navas, Jackson Killian, Rachel Guo





















https://lily-x.github.io lily\_xu@g.harvard.edu

### **Computational challenges** Deploying AI in the real world

### AI has much to learn from conservation and other real-world challenges!



### Lessons Learned

#### **Project design + scoping**

- Begin with simple computational approaches
- Incremental deployment before ambitious project design

#### Deployment

- Real-world deployment is necessary for • effective technology transfer
- Large-scale deployment requires quality • engineering
- Evaluate with self-contained experiments

### **Marrying research + practice**

- Integrate domain expertise into algorithm design
- Consider real-world constraints as research challenges, not limitations
- Limited data inspire research directions to close the gap

